

WECC REMTF

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## Background—Retirement of REEC\_B Model

As renewable penetration increased within the Western Interconnection, the WECC Modeling and Validation Work Group (MVWG) developed generic models for the inverter-based generators. The general model structures include the renewable-energy generator/converter (REGC) modules as the interface with the grid, the renewable-energy electrical controls (REEC) modules for the electrical controls of the individual units, and the renewable-energy plant controller (REPC) modules for the plant-level controls. The REGC and REPC models are common among many types of inverter-based generators. The selection of type of REEC model can vary among wind, solar PV, and energy storage plants. Originally, in 2014, the REEC\_A model was developed for use for wind turbine generators, and, although it could (and had) been used to model PV inverters, some people within WECC requested and supported the development of the REEC\_B model, a simplified version of REEC\_A, for modeling solar PV. In 2015, the REEC\_C model was developed for energy storage. As such, most people started using REEC\_B for modeling solar PV.

Several disturbance events of large-scale solar PV generation loss occurred since 2017. Investigation of these events revealed that many solar PV plants used momentary cessation as a means of ride-through for abnormal voltage conditions. Momentary cessation is when no current is put into the grid by the inverters during low- or high-voltage conditions outside the continuous operating ranges. Such momentary cessation behaviors cannot be modeled using the REEC\_B model approved for solar PV inverters. In 2018, the WECC MVWG modified the approval of REEC models to —

- REEC\_A for wind, and solar PV, if using momentary cessation
- REEC\_B for solar PV not using momentary cessation

However, such distinction between the REEC\_A and REEC\_B models for solar PV inverters may be neglected or cause confusion. The REEC\_B model, simplified from the REEC\_A model, does not have much more benefit or modeling capability than the REEC\_A model. Therefore, the WECCMVWG approved the retirement of the REEC\_B model in April 2019. Future submission of the REEC\_B model is no longer accepted and the current REEC\_B models in the WECC master dynamic file will be converted to REEC\_A models.

Conversion of the REEC\_B model to the REEC\_A model includes the following:

1. For inverters using momentary cessation, the conversion to REEC\_A should include properly accounting for momentary cessation setting. The REEC\_A model has limitations on modeling



- momentary cessation.<sup>1</sup> A new model in development, REEC\_D,<sup>2</sup> will be fully capable of modeling momentary cessation.
- 2. For inverters not using momentary cessation, the conversion could be done by adding parameters required by the REEC\_A model.

The section below addresses the second scenario—converting REEC\_B to REEC\_A without momentary cessation.

## Converting REEC\_B to REEC\_A without Momentary Cessation

REEC\_B model was a simplified version of REEC\_A. A comparison between the model structures of REEC\_A (Figure 1) and RECC\_B (Figure 2) shows the following differences when modeling a solar PV plant:

- 1. The switch in the Kqv reactive current injection arm in REEC\_A, but not in RECC\_B.
- 2. VDL blocks in REEC\_A, but not in REEC\_B.
- 3. There are a few other parameters in REEC\_A, that are not in REEC\_B—thld2, vref1, pflag.

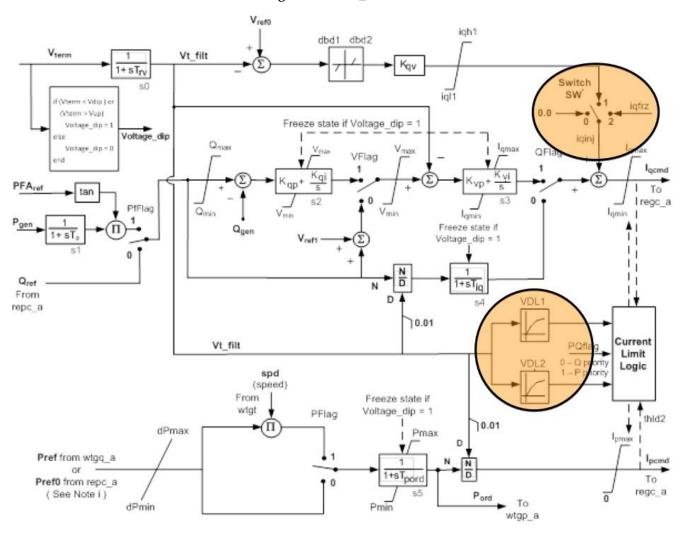
 $<sup>{}^2</sup>https://www.wecc.org/\ layouts/15/WopiFrame.aspx?sourcedoc=/Administrative/Memo\%20RES\%20Modeling\%20Updates-\%20Pourbeik.pdf&action=default&DefaultItemOpen=1$ 



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<sup>&</sup>lt;sup>1</sup>https://www.nerc.com/comm/PC/NERCModelingNotifications/Modeling Notification - Modeling Momentary Cessation - 2018-02-27.pdf

Figure 1: REEC\_A Model





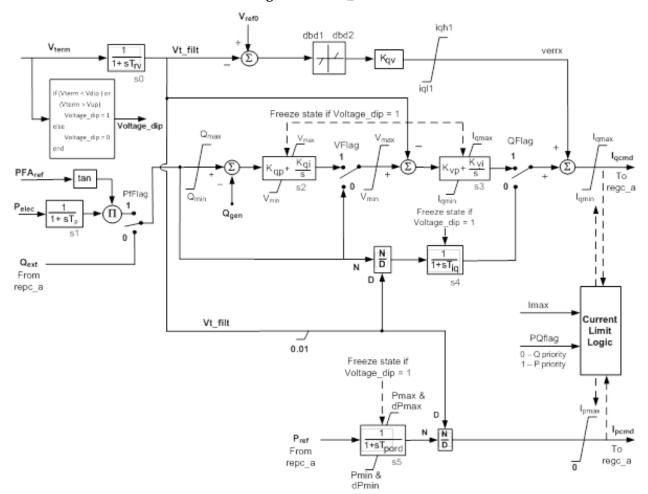


Figure 2: REEC\_B Model

## Parameters for Kqv reactive current injection

The reactive current injection switch in REEC\_A controls the current injection as described below:

- Under normal operating conditions,  $voltage\_dip = 0$  and SW = 0.
- When *voltage\_dip* changes to 1, SW is set to 1 to enable current injection.
- When *voltage\_dip* changes from 1 to 0, depending upon the value of *thld*, one of the following actions takes place:
  - $\circ$  If *thld* = 0, SW is reset to 0 immediately and there is no more current injection from the arm.
  - o If thld > 0, SW is set to 2 for thld seconds. During this thld seconds, the current injection is set to iqfrz. After thld seconds, SW is reset to 0; there is no more current injection from the arm.
  - o If thld < 0, SW is held at 1 for |thld| seconds and the Kqv control continues during this period. After |thld| seconds, SW is reset to 0; there is no more current injection from the arm.

The state transition is shown in Figure 3.



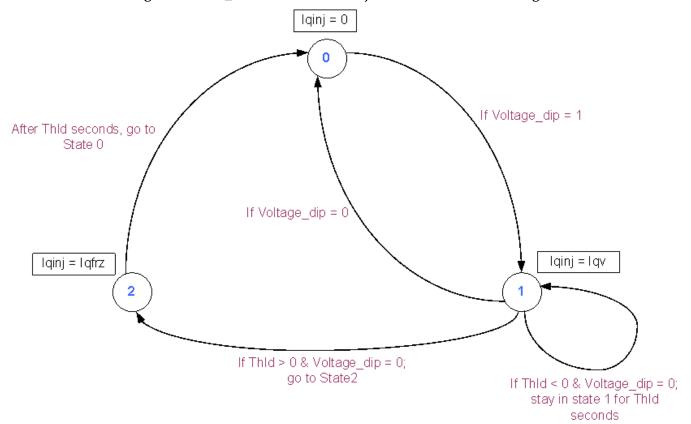


Figure 3: REEC\_A Reactive Current Injection State Transition Diagram

The REEC\_B model always have current injection logic on.

When converting REEC\_B to REEC\_A, set *thld* = 0 and *iqfrz* = 0 in the REEC\_A model. The conversion is not strictly equivalent between the REEC\_A and REEC\_B, as the REEC\_A will check for voltage\_dip = 1 to activate the reactive current injection, which is a better representation of the actual inverter controls. In case the REEC\_B model does not use voltage\_dip logic at all, i.e., vdip and vup parameters are set so that voltage\_dip is never activated, a thorough review is required to check the condition under which the kqv current injection is applied in the actual inverters before converting the model.

Note that another possible conversion is to use the REEC\_C model and set Pmin = 0; SOCini = 0.5; SOCmax = 1; SOCmin = 0, and T = 99999. This will disable the storage element, then all other parameters will be converted one to one. The VDL parameters can be set as described in the next section.

#### Parameters for VDL Blocks

VDL blocks (i.e., VDL1 and VDL2) in REEC\_A define the voltage-dependent current limits for active current and reactive current, respectively. They are piecewise linear curves defined to four break points. The VDL blocks can be used to model inverter momentary cessation by limiting currents to 0



<u>under/above the low/high momentary cessation voltage threshold.</u> When converting REEC\_B to REEC\_A, the following VLD parameters provide the same response as the original REEC\_B model.

Table 1: Converted VDL Parameters in REEC\_A

VD	L1	VD	L2
(vq1, iq1)	(-1.0, imax*)	(vp1, ip1)	(-1.0, imax)
(vq2, iq2)	(2.0, imax)	(vp2, ip2)	(2.0, imax)
(vq3, iq3)	(0,0)	(vp3, ip3)	(0,0)
(vq4, iq4)	(0,0)	(vp4, ip4)	(0,0)

### Other Parameters for REEC\_A

When converting to REEC\_A model, the following parameters need to be added:

**thld2** =  $\mathbf{0}$ — after *voltage\_dip* returns to 0, the active current command is held at the last value for *thld2* seconds.

 $\mathbf{vref1} = \mathbf{0} - \mathbf{user}$ -defined reference on the inner-loop voltage control.

**pflag** = 0—power reference is P instead of P multiplied by speed.

#### Case Studies

Several cases are presented below by changing the parameters in the original REEC\_B model to compare the performance of the conversion. The REEC\_B model parameters selected in the case studies are for demonstration and do not represent any actual plant.

#### Example 1

Nearly identical responses between REEC\_B model and converted REEC\_A model

Under a deep fault that activates voltage\_dip logic in both the REEC\_B and the converted REEC\_A model, the two models produce nearly identical responses.

The original REEC\_B parameters and converted REEC\_A parameters are shown in Table 2.

Table 2: REEC\_B Converted to REEC\_A — Example 1

	Original REEC_B	Converted REEC_A
vdip	0.5	0.5
vup	1.1	1.1
trv	0.01	0.01
dbd1	-0.1	-0.1
dbd2	0.1	0.1
kqv	2	2
iqh1	1	1



iql1	-1	-1
vref0	1	1
iqfrz		0
thld		0
thld2		0
tp	0.01	0.01
qmax	0.6	0.6
qmin	-0.6	-0.6
vmax	1.2	1.2
vmin	0.8	0.8
kqp	1	1
kqi	1	1
kvp	1	1
kvi	1	1
vref1		0
tiq	0.01	0.01
dpmax	1	1
dpmin	-1	-1
pmax	1	1
pmin	0	0
imax	1	1
tpord	0.01	0.01
pfflag	0	0
vflag	1	1
qflag	1	1
pflag		0
pqflag	0	0
vq1		-1.0
iq1		1.0
vq2		2.0
iq2		1.0
vq3		0.0
iq3		0.0
vq4		0.0
iq4		0.0
vp1		-1.0
ip1		1.0
vp2		2.0
ip2		1.0
vp3		0.0
ip3		0.0



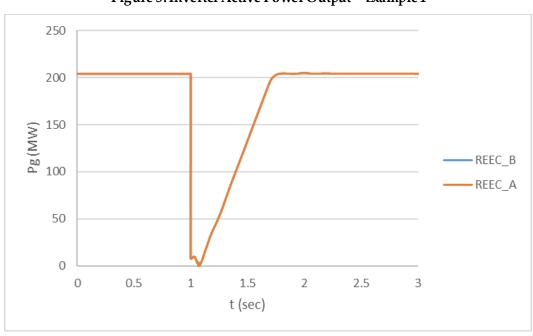
vp4	0.0
ip4	0.0

A four-cycle, three-phase-to-ground bolted fault is applied at the point of interconnection to the transmission grid. The converted model produced a response identical to the original model. The inverter response is shown in Figures 4, 5, and 6. Note that the plots of the REEC\_B model and the REEC\_A model completely overlap.

1.4 1.2 1 8.0 (b.u.) REEC\_B REEC\_A 0.4 0.2 0 0 0.5 1.5 1 2 2.5 3 t (sec)

Figure 4: Inverter Terminal Voltage—Example 1







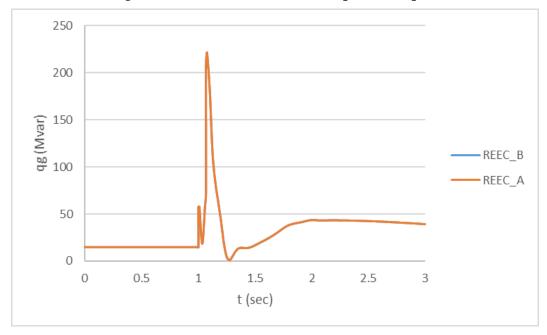


Figure 6: Inverter Reactive Power Output—Example 1

#### Example 2

### Reasonably close responses between REEC\_B model and converted REEC\_A model

Under a disturbance that would not activate voltage\_dip logic in the converted REEC\_A model, there might be noticeable but acceptable differences between the REEC\_B and the converted REEC\_A responses.

To demonstrate the influence of the Kqv reactive current injection arm under normal voltage conditions (voltage\_dip is 0, meaning no Kqv path in REEC\_A model), a four-cycle, three-phase-to-ground fault with a fault impedance (to make the transient voltage in range between vdip and vup) is applied at the point of interconnection to the transmission grid. The deadband parameters in the original REEC\_B model are modified from Table 2 to those in Table 3 to amplify the Kqv path influence. The inverter response is shown in Figures 7, 8, 9, and 10. There is only a small difference in the reactive power outputs, which are caused by the different reactive current commands within normal voltage range.

Original REEC\_B Converted REEC\_A vdip 0.5 0.5 1.1 1.1 vup 0.01 trv 0.01 dbd1 -0.05 -0.05dbd2 0.05 0.05

Table 3: REEC\_B Converted to REEC\_A — Example 2



kqv	2	2
iqh1	1	1
iql1	-1	-1
vref0	1	1
iqfrz		0
thld		0
thld2		0
tp	0.01	0.01
qmax	0.6	0.6
qmin	-0.6	-0.6
vmax	1.2	1.2
vmin	0.8	0.8
kqp	1	1
kqi	1	1
kvp	1	1
kvi	1	1
vref1		0
tiq	0.01	0.01
dpmax	1	1
dpmin	-1	-1
pmax	1	1
pmin	0	0
imax	1	1
tpord	0.01	0.01
pfflag	0	0
vflag	1	1
qflag	1	1
pflag		0
pqflag	0	0
vq1		-1.0
iq1		1.0
vq2		2.0
iq2		1.0
vq3		0.0
iq3		0.0
vq4		0.0
iq4		0.0
vp1		-1.0
ip1		1.0
vp2		2.0
ip2		1.0



vp3	0.0
ip3	0.0
vp4	0.0
ip4	0.0

Figure 7: Comparison of lq Command between REEC\_A and REEC\_B — Example 2

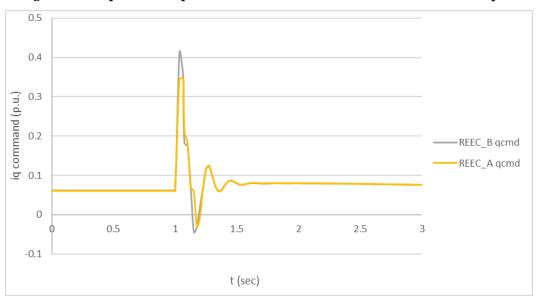
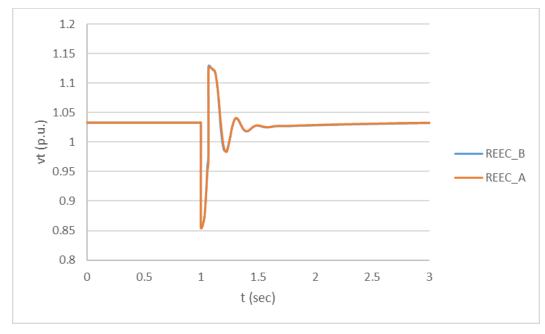


Figure 8: Inverter Terminal Voltage—Example 2





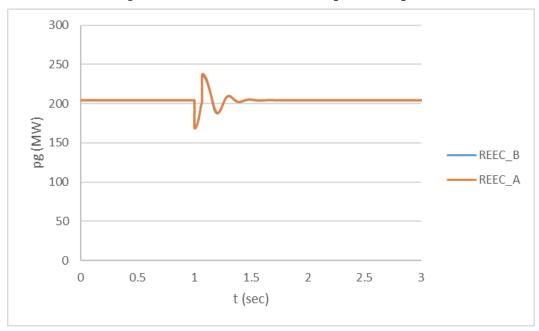
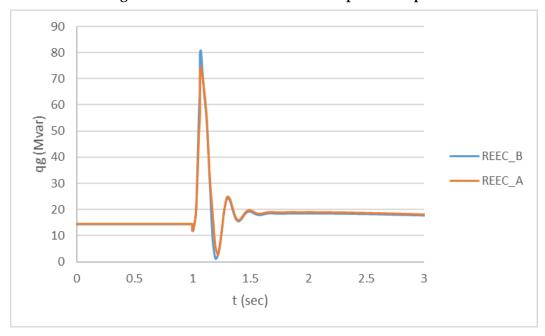


Figure 9: Inverter Active Power Output — Example 2





Note that the vdip, vup, dbd1 and dbd2 parameters were intentionally set in the case study for demonstration purposes. Typically, for inverters not using momentary cessation, vdip is 0.9 and vup is 1.1, and the control deadbands match the voltage dip setup, i.e., dbd1 = vdip - 1 and dbd2 = vup - 1. Under this typical setting, there is no difference between the converted REEC\_A and the original REEC\_B for all operating conditions.



### Example 3

Converting REEC\_B model that does not use voltage\_dip logic

If the REEC\_B model uses Kqv control (i.e., kqv>0), but not the voltage\_dip logic, converting to REEC\_A model could require re-tuning of the model.

Table 4 shows the conversion, in this case, involves changing vdip and vup parameters between the REEC\_B and the REEC\_A models. The setup of the REEC\_B model relies on Kqv current injection for voltage control. Without modifying vdip and vup in REEC\_A to activate Kqv control, the REEC\_A produces a different response than the REEC\_B model.

Table 4: REEC\_B Converted to REEC\_A — Example 3

	Original REEC_B	Converted REEC_A
vdip	-99	0.95
vup	99	1.05
trv	0.02	0.02
dbd1	-0.05	-0.05
dbd2	0.05	0.05
kqv	2	2
iqh1	1.25	1.25
iql1	-1.05	-1.05
vref0	1	1
iqfrz		0
thld		0
thld2		0
tp	0.05	0.05
qmax	1.0	1.0
qmin	-1.0	-1.0
vmax	1.1	1.1
vmin	0.9	0.9
kqp	1	1
kqi	0	0
kvp	1	1
kvi	0	0
vref1		0
tiq	0.3	0.3
dpmax	99	99
dpmin	-99	-99
pmax	1	1
pmin	0	0
imax	1.3	1.3



tpord	0.02	0.02
pfflag	0	0
vflag	1	1
qflag	0	0
pflag		0
pqflag	0	0
vq1		-1.0
iq1		1.3
vq2		2.0
iq2		1.3
vq3		0.0
iq3		0.0
vq4		0.0
iq4		0.0
vp1		-1.0
ip1		1.3
vp2		2.0
ip2		1.3
vp3		0.0
ip3		0.0
vp4		0.0
ip4		0.0

 $Figure~11: Comparison~of~iq~Command~between~REEC\_A~and~REEC\_B$ 

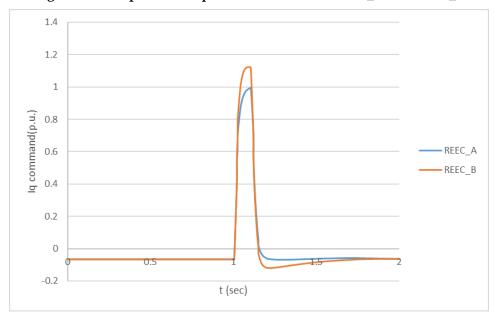




Figure 12: Inverter Terminal Voltage – Example 3

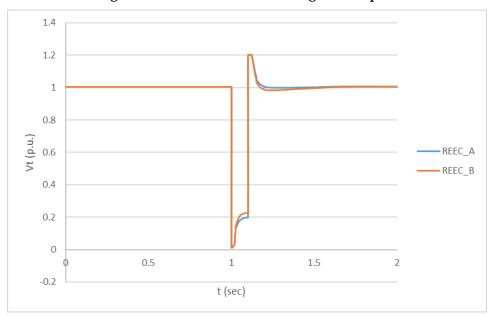
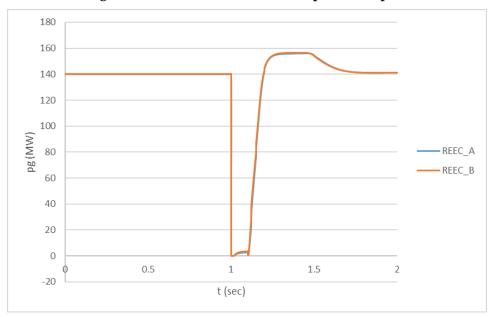


Figure 13: Inverter Active Power Output – Example 3



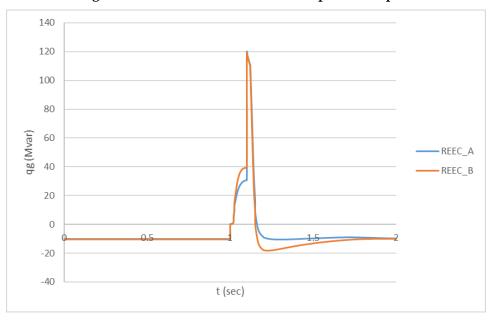


Figure 14: Inverter Reactive Power Output — Example 3

In this example, changing vdip and vup parameters achieves reasonable responses from the converted REEC\_A model, as shown in Figures 11 through 14. It may not always be proper to change vdip and vup parameters, as the voltage\_dip logic impacts the other control loops as well. A thorough review of the models is recommended.

## **Proposed Actions**

Conversion from REEC\_B to REEC\_A could be done systematically without losing any model accuracy or introducing any modeling errors in most cases. WECC recommends converting all REEC\_B models in the WECC master dynamic file to REEC\_A.

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